A guide to using the Hyperion Emeter PC Interface software

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What does this software do?

Using an Hyperion Emeter and Hyperion PC interface cable it allows real-time measurements to be displayed, stored and recalled for analysis. This can be useful for many applications:

- Motor characterisation (efficiency and static thrust)
- Battery discharge / charge analysis
- Matching appropriate propellers to your motor-battery-controller combination
- And more...

What are the software and hardware requirements?

- An Hyperion Emeter
- The Hyperion PC interface cable

The software will run on very simple hardware, common even in older laptops:

- A PC with Intel Pentium processor (equivalent, or higher)
- A free serial port (a USB to serial adapter can be used)
- 5 MB free hard disk space
- 32 MB memory
- Windows 98 or higher OS (Windows 2000, NT, XP)

Installation

The software is supplied as a compressed 'zip' file in order to save space. Please save this file and 'unzip' the contents to a directory ready for installation. Following 'unzipping' you should see the following installation files:

🔁 D:\install				ſ	
File Edit View Favorites Tools	; Help				-
🖙 Back 👻 🤿 👻 🔂 🧟 Search	Folders 🤅	3 4 4 :	X ທ ⊞ •		
Address 🗋 D:\install				-	∂G0
	Emeter			setup.exe	
install	Interface.msi				
Select an item to view its description.					
See also:	setup.ini				
My Documents					
My Network Places					
My Computer					
5 object(s)		5.02 M	B 📃 My	Computer	

These files will use 5 MB of disk space.

To start the installation of the software 'double-click' the setup program 'setup.exe' and follow the on-screen instructions.

The installation program will create the following:

- A shortcut called 'Emeter' on the desktop
- A shortcut to the Emeter datafiles called 'Shortcut to data' on the desktop
- An entry on the start menu of 'Emeter' under 'Hyperion'
- A directory on your first hard disk, under the 'Program Files' directory called 'Emeter Interface' (i.e. C:\Program Files\Emeter Interface\data) and 'Emeter Interface\data' for file storage

Running the software

From the 'start' menu of Windows select 'Programs', 'Hyperion', 'Emeter' and click on the Emeter listing. This will start the software and you will be presented with the software front-panel similar to that below (with a blank graph).

Emeter Interface ¥1.2.5					- D ×
Print Export Help					
Direct Measu	rement	Ĺ	Thrust / Po	ower / Efficiency	
Volts A (out) Watts A (in)	File RPM Eff.	Start Ah out Ah in	Stop Time	Max Volts 0.00 A (out) 0.00 A (in) 0.00	Min 0.00 0.00 0.00
Description		× Y	Save Description	RPM 0.00 Eff. 0.00 Ah out 0.00 Ah in 0.00	0.00 0.00 0.00 0.00
Y-Axis Amps (out) ▼	X-Axis Volts	•	Grid Point:	s Only 💌 🛛 3D Ba	

This software will allow new measurements to be recorded, data from previous tests to be reloaded, analyses the data for minimum and maximum figures and selection of graph axes.

Displaying previously recorded data

Clicking the 'Open File' button will open a windows dialog box to select the file from the emeter directory:

Open					<u>? ×</u>
Look in:	🔁 emeter		•	🗕 🗈 💣 🎟	-
History Desktop My Documents	install New Folder emeter.txt pico_o_2000 pico_o_2000 pico_o_2000 pico_o_2000 test.txt test2.txt	txt _a.txt _b.txt _c.txt			
My Computer	File name: Files of type:	TXT Files (*.txt)		•	Open Cancel

To select the required file 'double click' on the item in the list. The top of the display will now change similar to that below:

Emeter Interface ¥1.2.5		
Print Export Help		
Direct Measurement	Thrust /	Power / Efficiency
Open File	Start Stop	Max Min
	An out An in Time	Voits 12.33 10.35 A (out) 12.41 0.04 A (in) 0 0
L:\Program Files\Emeter Interface\data\rcer_10	JX47.txt	RPM 1785 0
Description		Eff. 0 0
RCer DIY motor 12T 24AWG	▲ Save ↓ Description	Ahout 0 0 Ahin 0 0
Y-Axis X-Axis Amps (out) Volts	Grid Poi	nts Only 💌 3D Ball 💌

Displayed on the right will be the measured maximum and minimum recorded values, and on the left will be shown the path and filename opened (being analysed). A default graph of 'Amps' against 'Volts' will also be displayed.

The axes of the graph can be selected from the two drop-down boxes labelled 'Y-Axis' and 'X-Axis. The options for both boxes are shown below:



These options are:

- 'Volts' measured voltage
- 'Amps (out)' current from source to load
- 'Amps (in)' current from load to source
- 'RPM' measured RPM
- 'Efficiency' measured motor efficiency
- 'Ah (out)' the charge drained from source to load
- 'Ah (in)' the charge drained from load to source
- 'Time' time
- 'Watts' the electrical power being delivered to the load

Selection of any new graph axis causes the graph to be redrawn. The 'Grid' control box will display (or remove) gridlines from the graph. The graph can be displayed as 'points only' or 'line'. The point marker can be selected As different types and is shown below:



It is possible to analyse an individual data point. By 'clicking' (selecting) an individual data-point it becomes highlighted and the data for that point is displayed on the top right-hand-side of the graph.



A permanent description can be added in the free-form text field. Pressing 'save description' will save this information with the file for later analysis.

Description					Eff.	0	0
RCer DIY motor 12T 24AWG			•	Save Description	Ah out Ah in	0	0
Y-Axis	X-Axis						
Amps (out)	Volts	•		Grid Poi	nts Only	<u> </u>	D Ball 🔽

Selecting the 'Print' menu option will display a printer dialog box where the printer can be selected and the graph printed. Alternatively you can select the 'Export' option that will export either the window, or just the graph, to either of two common graphics image formats; jpg or png.

Examples of both types of exported images are shown below; first for the graph and second for the window:





Recording from the Emeter

Before starting to record data please connect the Emeter to the PC with the dedicated interface cable and turn the Emeter switch 'ON'.

The software will automatically query your computer and identify what serial ports are present in your PC (COM1-18), with the first available port being displayed in the drop down box:

🐂 Emeter Interface ¥1.1.1			
Print Help			
COM3	Open File	Start	Stop

Please identify which serial port is connected to the Emeter via selection of the appropriate port in the drop-down box and press the 'Start' button. [If you find no serial ports listed in the drop-down box, it may be that your PC is set in "CMOS Setup" to disable all serial ports. Consult your PC manual for instructions on entering CMOS Setup mode. Most modern PCs have an "automatic" setting for serial ports in CMOS, and this should be tried first. We do not support PC setup questions, so ask a friend if you get stuck, please.]

A Windows file dialog box will be opened in which you should enter the filename you wish to use for the recorded data and press 'Save':

Save		? ×
Save in:	: 🔄 emeter 💽 🔶 🖆 🏢 -	
Itistory Desktop My Documents	install C:\emeter\ New Folder emeter.txt pico_o_2000.txt pico_o_2000_a.txt pico_o_2000_b.txt pico_o_2000_c.txt test.txt test.txt test2.txt	
My Computer	File name: run12 Save as type: Text Files (*.txt)	Save Cancel

The top part of the display will now change and present live data values, together with the maximum and minimum values. The graph will start to display the data points being measured.

In the same way as for opening data files the graph axes can be selected for the parameters of interest.

Following test completion pressing the 'Stop' button will finish recording and finalise the recorded file.



File storage formats

Files are stored in the emeter directory in three formats:

- **'.txt.'** text file containing the raw data from the Emeter
- **'.csv'** comma separated variable files that contain the processed data in a universally accepted format that can be read by most packages.
- '.xls' Microsoft Excel spreadsheet containing the processed data

Accessing post measurement thrust and efficiency analysis

The software has a second section that can be accessed via clicking the top 'tab' (Thrust / Power / Efficiency). For the props in the database this will allow a prop to be selected from the drop-down box and this causes the prop constants to be loaded. These constants are displayed on the right hand side of the window. These are based on experimental measurements and have proven to be quite accurate. In order to provide better accuracy compensation for temperature (Temp) and height above sea level (ASL) is included – in either Imperial or Metric units and accessed via the button to the right.

Emeter Interface ¥1.2.5	
Print Export Help	
Direct Measurement	Thrust / Power / Efficiency
Propeller	Constant Pfactor Density Comp.
APC Slow Fly 10x4.7	Thrust 12.9 2.18 1.00557
ASL (m) Temp. (C)	Power 0.18744 3.3 1.01413

The prop database is not exhaustive and not yet completely filled – a download file will be made available (coeffs.csv) and also announced in RCGroups as testing progresses.

Please note: The propeller database is not yet complete; the propeller coefficients rely on a series of labour intensive thrust-stand and dynometer measurements of various propellers. It is with gratitude that I thank Phil Millener (Doc Kiwi) for the thrust data to-date and the Hyperion team (Phil Connolly) for the dynometer measurements. As such you will find that some of the props listed only have coefficients for absorbed power and some for thrust only. As testing progresses an updated database file will be available for download from www.hyperion.hk. This file (*'coeffs.csv'*) should be downloaded and placed in the Emeter datafiles directory (called 'Shortcut to data' on the desktop) of your hard disk and will automatically update the software database. Please be patient – this testing will take some time.



These coefficients are of the form:

Thrust or Power = Constant x (RPM/1000)^Pfactor

Where Pfactor is ~ 2 for Thrust estimation and Pfactor ~ 3 for Power estimation.

In order to maximise the accuracy of the estimation, compensation is available for the air density in relation to the reference measurements. The default selection is 0 metres Above Sea Level (ASL) and a temperature of 20 °C. Entry of alternate figures in these boxes causes the graph to be re-drawn and the Density Compensation figures to be calculated. In general this compensation is carried out as:

Thrust or Power =Density Compensation x Constant x (RPM/1000)^Pfactor

The selection of the graph type is shown below. There are eight graphs available (for props with both sets of constants measured):

- Thrust / RPM. The calculated thrust against measured RPM for the prop.
- Thrust / Current. The calculated thrust against measured current for the prop.
- Thrust / Voltage. The calculated thrust against measured voltage for the prop.
- Thrust / Power. The calculated thrust against measured power for the prop.
- Efficiency / RPM. The calculated motor efficiency against measured RPM for the prop.
- Efficiency / Current. The calculated motor efficiency against measured current for the prop.
- Efficiency / Voltage. The calculated motor efficiency against measured voltage for the prop.
- Efficiency / Power. The calculated motor efficiency against measured power for the prop.

The graph window behaves in a similar manner to that for the previous screen; individual data points can be accessed and the point and grid options can be selected. There are 8 types of graph that are available and shown below:

Graph Type	
Thrust / RPM	Grid 🛛 Points Only 💌 3D Ball 💌
Thrust / RPM	
Thrust / Current	
Thrust / Voltage	
Thrust / Power	
Efficiency / RPM	
Efficiency / Current	
Efficiency / Voltage	
Efficiency / Power	

.... And finally

The Emeter, interface and software provide a unique analysis toolset that will make you wonder how you 'made do' without it before. If there is something that you want to see in this software then get in touch!